

622.92

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1

[1]

[2]

2.

1.

2.

3.

:

:

:

P_x ,

Z.

h

V_n ,

210÷

, 2,62÷2,82 / ³).

(

)

8,8 / (

n = 1600 /).

, 400-630-800 /

, 200-400-600-800-1000

25

30

y, ,

[3].

6 13 .

160 50 400/315 6-14.50% 88 90. 513-81

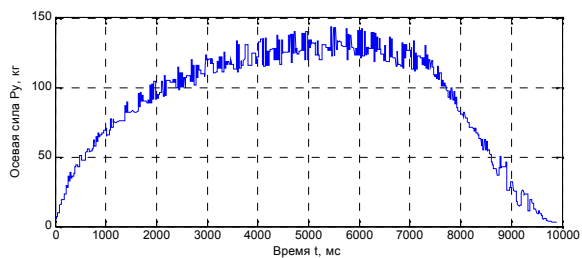
, [4].

, [5-6].

-5,

Pico ADC-16

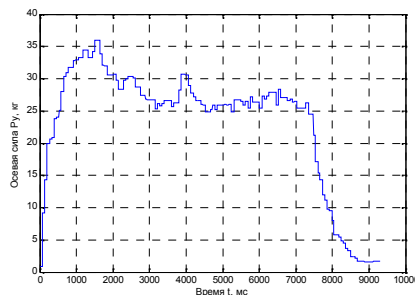
y (. 1)



. 1.

y

S=400 / , t=800



. 2.

y

S=400 / , t=800

(. 1).

y

S=400 / 768

315 851 , S=800 / - 242

S=630 / - 268 644 .

S=630 / - 278

S=400 / 730

218 730 , S=800 / - 296

775 .

1.

		y	y
200	400	8,6	61,4
400	400	10,8	77,2
600	400	17,1	99,5
800	400	26,8	121,8
200	630	7,9	95,5
400	630	15,7	112,8
600	630	22,6	139,0
800	630	37,3	155,0
200	800	19,2	119,7
400	800	23,2	130,0
600	800	50,2	155,0
800	800	57,6	173,2

(.2, .3, .4).

2.

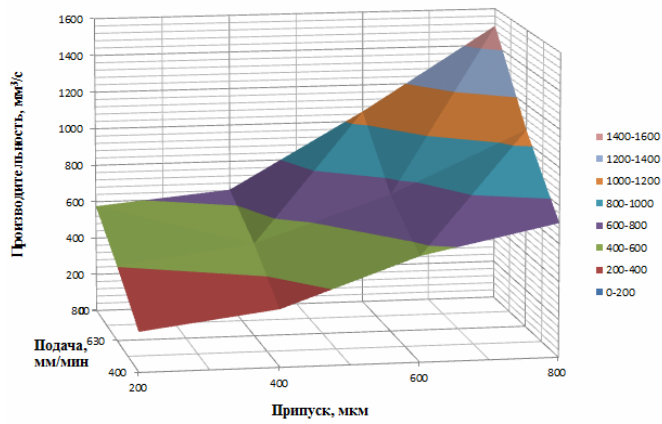
		^{3/}	^{3/}
200	400	310	212
400	400	493	305
600	400	541	560
800	400	828	709
200	630	390	405
400	630	496	498
600	630	824	738
800	630	1120	1065
200	800	471	576
400	800	597	644
600	800	1100	1054
800	800	1253	1507

480 ^{3/} ,
447 ^{3/} .

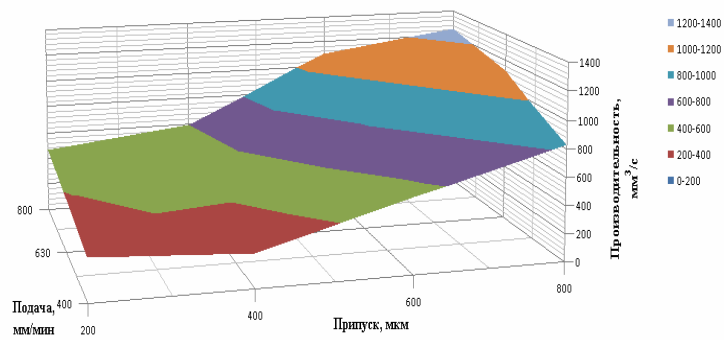
(400 /)

- 945 ^{3/} .

855 ^{3/} , S=800 /



. 3.



. 4.

, . . .

[7].

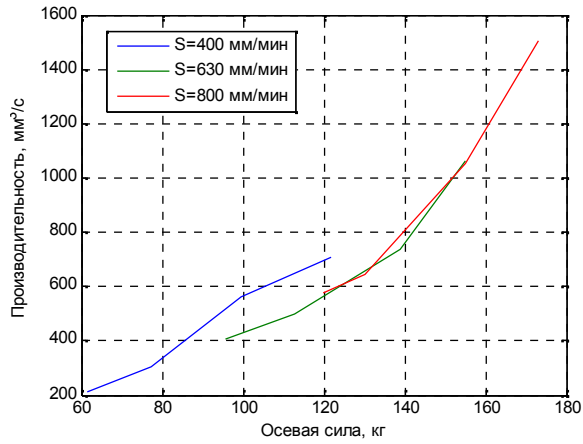
$$= 638 - 1,4 \cdot S - 1,3 \cdot t + 0,0014 \cdot S^2 + 0,0018 \cdot t^2, \quad (1)$$

; S – , / ; t – , .

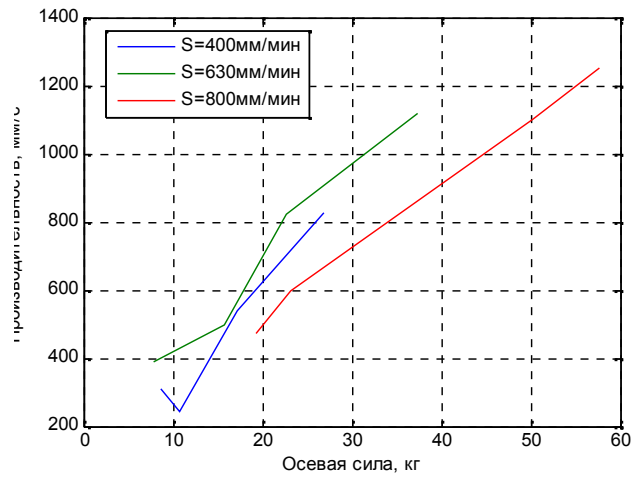
(1)

(.1)

(.5,6).



5.



6.

3.

1507 / 800 / 212 400 / 3 / 400 / 630 /

: 1.

), 1976, 160 . 2.

: , 1984 – 224 . 3.

2005. . 164 – 174 4.

.49-58. 5.

2004. – .164 – 174. 6. Gorobez I., Navka I., Lapajeva I., Schaban K. Die Parameter der Adaptronsysteme der Drehmaschinen – Modern Technologies, Quality and Restructuring International Conference N.C.M.R – Bulletin of the Politechnic institute of Jassy, Iassy, Roma