

PREDICTION OF CUTTING TOOLS WEAR FOR LATHES

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Summary: A mathematical model to estimate the average number of parts, processing which is possible to achieve the criterion of maximum allowable wear on the back of the cutter heavy lathe, and the maximum allowable amount of tool material, removed from the front surface of the tool.

Keywords: playground wear, hole wear, contact stress, cutting edge, cutting temperature, adhesive wear, the adequacy of the models.

While working on the details of heavy lathes main types of fault-alloy cutters are wearing them on the front and back surfaces, as well as fatigue damage cutting plates. Determination of maximum permissible values of wear on the back surface were carried out based on economic criteria.

For practical use have a value of mathematical models to estimate the average number of parts, which was processed to reaching the criterion of wear.

Evaluation of resistance of cutting tool criterion for maximum allowable wear on the rear surface

Developing a model to assess the average number of parts, processing which is possible to achieve the criterion of maximum allowable wear on the rear surface is made to the following basic assumptions:

- criterion of maximum allowable adhesion wear on the back of the formation of a high wear areas $[h_{zp}] = 1,2 \text{ mm}$;
- basic mechanism of cutting tool wear on the back of the adhesion mechanism is;
- average temperature of the material the instrument is fixed for the whole region back surface contact with the processed material;
- stress of the cutting tool is a flat;
- tool material in contact with the workpiece the tool is characterized by a constant value for the whole region stresses fluidity R_{cm} ;
- number of parts, processing which is possible to achieve the maximum allowable height of platform wear $[h_{zp}]$ is:

$$N_{0,1} = \frac{[h_{zp}]}{h_{zp}},$$

where h_{zp} – increased wear platform for processing one part.

Based on studies of normal contact pressure distribution on the back of the instrument $q(x)$ can be represented by dependence:

$$q(x) = q_{\max.z} \left(1 - \sqrt{\frac{x}{h_{zp}}} \right), \quad (1)$$

where h_{3n} – width areas of physical contact in this case – wear areas; x – distance from the cutting edge cutter; $q_{\max.z}$ – maximum contact pressure at the back of the:

$$q_{\max.z} = 2\tau_{\phi}(1,3 \pm \gamma) \pm \tau_{\phi} \sin 2\gamma, \quad (2)$$

(plus sign corresponds to negative front angles);

where τ_{ϕ} – tension changes in a layer that trimmed, with the average temperature at the site contact the back of the instrument with the processed material. To determine the value used τ_{ϕ} dependence:

$$\tau_{\phi} = 0,72R_g \cdot \delta_5^{0,6\delta_5},$$

where R_g – ultimate strength of the material processed at an average temperature at the site of contact; δ_5 – elongation of the material processed at an average temperature at the site of contact. To evaluate the quantities R_g , δ_5 used depends obtained on the basis of statistical data processing:

$$R_g(\Theta) = R_{g_0} \exp(a_1(\Theta_0 - \Theta)), \quad \delta_5(\Theta) = \delta_{5_0} \exp(b_1(\Theta - \Theta_0)), \quad (3)$$

where Θ – average temperature cutting; R_{g_0} , δ_{5_0} – Tensile strength and elongation of the material processed at a temperature test $\Theta_0 = 700^\circ\text{C}$; a_1 , b_1 – coefficients determined by the method of least squares.

The average contact pressure at the back of the instrument can measure the expression q :

$$q = \frac{1}{h_{zp}} \int_0^{h_{zp}} q_{\max.z} \left(1 - \sqrt{\frac{x}{h_{zp}}} \right) dx.$$

To determine the average temperature dependence of cutting used by the author, obtained by statistical processing of experimental data:

$$\Theta = a_1 v^{a_2} s^{a_3} t^{a_4}, \quad (4)$$

where a_1 , a_2 , a_3 , a_4 – calculated ratios determined by the method of least squares.

To determine the number of the parts to achieve the criterion of maximum allowable adhesion wear on the back of the take that amount of material d , removed from the back of the instrument for the elementary time interval $d\tau$ physical contact with the workpiece material back of the cutter, can be estimated from geometrical considerations:

$$dQ = b \left(h \cdot dh \cdot \tan \alpha + \frac{1}{2} dh^2 \cdot \tan^2 \alpha \cdot \tan \gamma \right);$$

$$b = \frac{t}{\sin \phi}, \quad (5)$$

where h – altitude areas of wear, which corresponds to the moment of time τ ; dh – increase in areas of wear during $d\tau$; γ , α , ϕ – under the front corner and rear corner of the main corner in terms of the instrument; t – depth of cut.

On the other hand, the volume of material removed from the rear surface during $d\tau$, measured the expression:

$$dQ = P_u v \eta \delta b \cdot d\tau, \eta = \frac{q}{q^*}, \quad (6)$$

where P_u – the likelihood that the zone of adhesion failure of communication is not in the treated material, and material of the instrument; v – speed cutting; δ – thickness of which is the destruction of products bearing adhesive ties: $\delta \cong 3 \cdot 10^{-10} \dots 5 \cdot 10^{-9} \text{ m}$; η – the relative share areas of plastic surface microirregularity crumple in contact with the back of the instrument of processed material; q^* – maximum pressure required to crumple the full surface microirregularity processed material at the site of contact, estimated the expression:

$$q^* = 2,5R_e(1 - \mu), \quad (7)$$

where R_e – meaning limits yield of processed materials in accordance with the average temperature in the cutting zone; μ – constant friction.

If the average pressure at the site of contact, the workpiece material with the rear surface instrumente such that the value $\eta > 1$, we adopted $\eta = 1$. Size P_u can be estimated from the ratio of the critical crack lengths Hryffitsa that triggered the destruction of adhesion due:

$$P_u = \frac{l_u}{l_u + l_m}, \frac{l_u}{l_m} = \frac{R_m^2}{R_u^2}$$

where l_u, l_m – under the critical length of cracks in the surface layers of tool and workpiece material; R_u, R_m – tensile strength of the material and tool material processed at an average temperature at the site of contact. Taking the tool material and workpiece material hard plastic, the expression $\frac{R_m^2}{R_u^2}$ can be replaced by $\frac{R_e^2}{R_{eu}^2}$, where R_e, R_{eu} – border fluidity workpiece material and tool material at an average temperature at the site of contact, respectively. To determine the value of R_e used the dependence obtained by statistical processing of experimental data:

$$R_e(\Theta) = R_{e_0} \cdot \exp(b(\Theta_0 - \Theta)), \quad (8)$$

where Θ – the average temperature at the site of contact; R_{e_0} – the boundary strength of the material processed at a temperature test $\Theta_0 = 700^\circ\text{C}$; b – estimated coefficient determined by the method of least squares.

To determine the value of R_{eu} used dependence obtained by statistical processing of experimental data:

$$R_{eu} = 1,1R_T \left(\frac{\Theta_p}{\Theta} \right)^S \operatorname{arsh} \left(\frac{\dot{e} \cdot e}{\dot{e}_0 \cdot e_0} \right), \Theta \geq \Theta_p, \quad (9)$$

where \dot{e}_0, e_0 – intensity of deformation speed and intensity of accumulated strain during mechanical testing instrument; R_T – boundary strength of the material instrument at ambient temperature; S – constant characteristic of the tool material. If the temperature does

not exceed Θ cutting temperature early intensive removed Θ_p , instrumental material, it shall $R_{eu} = R_T$.

Comparing expressions (5) and (6) and respect for value dh^2 , as the second largest order little, after the integration date was changing altitude areas of wear from time to time contact:

$$h_{3n} = \sqrt{\frac{2\nu\tau\delta\eta P_u}{\tan\alpha}}, \quad \tau = \frac{l}{nS}, \quad (10)$$

where τ – time of processing one part, n – speed spindle.
After substituting the values of η and P_u obtained:

$$h_{3n} = \begin{cases} \sqrt{\frac{2 \cdot q_{\max} \cdot \nu \cdot \tau \cdot \delta}{4,5 \cdot \text{tg}\alpha(1-\mu)} \cdot \frac{R_e}{R_e^2 + R_{eu}^2}} & \text{if } \frac{q_{\max}}{7,5 \cdot R_e(1-\mu)} < 1 \\ \sqrt{\frac{2 \cdot \nu \cdot \tau \cdot \delta \cdot R_e^2}{\text{tg}\alpha \cdot (R_e^2 + R_{eu}^2)}} & \text{if } \frac{q_{\max}}{7,5 \cdot R_e(1-\mu)} \geq 1 \end{cases}$$

Then the number of parts, processing of which is available until a maximum allowable height of areas on the back of the depreciation is:

$$N_{0.1} = \begin{cases} [h_{3n}] \cdot \sqrt{\frac{3,75 \cdot \tan\alpha(1-\mu)(R_e^2 + R_{eu}^2)}{q_{\max}\nu\tau\delta R_s}} & \text{if } \frac{q_{\max}}{4,5R_e(1-\mu)} < 1 \\ [h_{3n}] \cdot \sqrt{\frac{\tan\alpha(R_e^2 + R_{eu}^2)}{2\nu\tau\delta R_e}} & \text{if } \frac{q_{\max}}{4,5R_e(1-\mu)} \geq 1 \end{cases} \quad (3.11)$$

The main mechanism of wear of cutting tools on the front surface are adhesion mechanism.

As a criterion of maximum allowable wear of the front surface is proposed to adopt the appearance of the front surface of the hole cutter wear depth $[h_{nn}]$.

Average number of blocks and treatment are possible until a maximum allowable depth of the hole wear, can be evaluated dependence:

$$N_{0.2} = \frac{[Q]}{Q}, \quad (12)$$

where $[Q]$ – the maximum allowable amount of tool material, removed from the front surface of the tool that meets $[h_{nn}]$; Q – volume of tool material, removed from the front surface of the tool during the processing of one part.

Value $[Q]$ is determined from geometric considerations the following expression:

$$[Q] = fb, \quad f = \frac{R^2\alpha - (R - [h_{nn}])l}{2}, \quad R = \frac{[h_{nn}]}{2} + \frac{l^2}{8[h_{nn}]}, \quad (13)$$

where l – length of the hole, b – width of the contact front surface of cutting tools with workpiece:

$$b = t / \sin\varphi.$$

The volume of material ∂Q , which is removed by an elementary interval of time of physical contact with the chip front surface of the tool is determined by the equation $d\tau$:

$$\partial Q = P_u v_c \eta \delta b \cdot dt, \quad v_c = \frac{v}{\xi}, \quad (14)$$

where P_u – the likelihood that the zone of adhesion failure of communication is not in the treated material, and material tools, assessments expression (9); v_c – speed chips on the front surface of the tool; v – speed cutting; ξ – coefficient of shrinkage of the chip; δ – thickness of the layer from which the products bearing the destruction of adhesive contacts: for most metals and alloys $\delta \cong 3 \cdot 10^{-10} \dots 5 \cdot 10^{-9} \text{ m}$; η – the relative share of regions full of plastic crumple mikronerivnostey chip surface in contact with the chip front surface:

$$\eta = \frac{q}{q^*}, \quad (15)$$

where q – the average pressure at the site of contact; q^* – average pressure required to crumple the full surface mikronerivnostey processed material on this site, estimated expression (7).

Based on studies of normal contact pressure distribution on the back of the instrument $q(x)$ can be represented by dependence:

$$q(x) = q_{\max.n} \left(1 - \sqrt{\frac{x}{l_k}} \right), \quad (16)$$

where l_k – chip contact length on the front surface:

$$l_k = a(\xi(1 - \tan \gamma) + \sec \gamma), \quad a = s \cdot \sin \varphi; \quad (17)$$

$q_{\max.n}$ – maximum normal pressure on the front surface:

$$q_{\max.n} = 2\tau_\phi(1,3 - \gamma). \quad (18)$$

The average value of normal pressure on the site of contact is:

$$q = \frac{1}{l_k} \int_0^{l_k} 2\tau_\phi(1,3 - \gamma) \left(1 - \sqrt{\frac{x}{l_k}} \right) \cdot dx. \quad (19)$$

The volume of material instrument removed from the front surface of the tool during the processing of one part τ , is recognized by dependence:

$$Q = \int_0^{\tau} P_u v_c \eta \delta b \cdot dt \quad (20)$$

Then, taking into account (17), (18):

$$Q = \frac{R_e^2}{R_e^2 + R_{eu}^2} \frac{v}{\xi} \frac{1}{q^*} \delta \frac{t}{\sin \varphi} \frac{1}{l_k} \int_0^{l_k} \int_0^{\tau} q_{\max} \left(1 - \sqrt{\frac{x}{l_k}} \right) dx dt. \quad (21)$$

On the assumption that the value of P_u , v_c , δ , b insignificant change in contact time, according to a theorem on the average integral obtained:

$$Q \cong \begin{cases} \frac{R_e}{R_e^2 + R_{eu}^2} \frac{v}{\xi} \delta \frac{q_{\max} t \tau}{4,5 \sin \varphi (1 - \mu)} & \text{if } \frac{q_{\max}}{4,5 R_e (1 - \mu)} < 1 \\ \frac{R_e^2}{R_e^2 + R_{eu}^2} \frac{v}{\xi} \delta \frac{t \tau}{\sin \varphi} & \text{if } \frac{q_{\max}}{4,5 R_e (1 - \mu)} \geq 1 \end{cases}. \quad (22)$$

Then the number of parts, processing which is possible to achieve the criterion of maximum permissible adhesion wear on the front surface is:

$$N_{0.2} = \begin{cases} \frac{[Q](R_e^2 + R_{eu}^2) \xi \cdot 4,5 \sin \varphi (1 - \mu)}{R_e v \delta q_{\max} t \tau} & \text{if } \frac{q_{\max}}{4,5 R_e (1 - \mu)} < 1 \\ \frac{[Q](R_e^2 + R_{eu}^2) \xi \sin \varphi}{R_e^2 v \delta t \tau} & \text{if } \frac{q_{\max}}{4,5 R_e (1 - \mu)} \geq 1 \end{cases}. \quad (23)$$

Evaluation of resistance of cutting tool criterion for maximum allowable wear size

For the finishing details stochastic equation has the form of wear:

$$\frac{dx}{dt} + dx = N(t), \quad (29)$$

Failure occurs when the details of its size to achieve maximum permissible value X_{max} , which happens after a random interval of tool $t = T_n$. Maximum permissible value of the parameter X_{max} determined from the condition of normal operation of the instrument. Operating time to failure T_n is a function of random arguments tool wear rate of change of C , ie $T_n = f(C)$. Failure occurs tool for achieving detail maximum permissible value X_{max} , what happens after a random period of time to process it.

Processed on a machine part has size, which tolerance is within the boundaries $X_{min} - X_{max}$. With increasing wear on the back of the instrument the size of parts changed. In average (Fig. 1) size of the parts is beyond the tolerance only after an interval time T_4 . But during work tool in the initial period of operation from T_1 to T_2 there is a danger for details, treated on the upper field tolerance, then the reliability of their increases. Excess of the tolerance field components finished to the lower limit of tolerance is possible at time $t = T_3$, with $T_2 < T_3$, a $T_3 < T_4$, as

$$(a, b) = \left(\frac{C}{\lambda}; \frac{C}{\lambda} + \Delta_{\max} \right) = (x_{\min}, x_{\max}). \quad (30)$$

Expected value and variance of dimensional stability of the instrument from the initial values gap Δ_0 , constant velocity component wear C and the coefficient of proportionality λ : $W(\Delta_0) = \delta(\Delta_0 - \Delta_{03})$:

$$W(C) = \delta(C - C_3), \quad W(\lambda) = \delta(\lambda - \lambda_3). \quad (31)$$

In this case, the probability density of the coordinates x in equation (29) at the initial time $t = 0$ is a delta-like function, ie

$$W_0(x) = \delta(x - x_0) = \delta\left(x - \frac{C_3}{\lambda} - \Delta_{03}\right). \quad (32)$$

The probability that a random x coordinate at the time t reaches the limits of the interval (x_{\min}, x_{\max}) through $Px_{\min, x_{\max}}(t, x)$. For continuous Markov process that can take wear and tear, the specific probability satisfies the equation:

$$\frac{\partial Px_{\min, \max}}{\partial t} = K_1(x_0) \frac{\partial Px_{\min, \max}}{\partial x_0} + \frac{1}{2} K_2(x_0) \frac{\partial^2 Px_{\min, \max}}{\partial x_0^2} \quad (33)$$

with initial conditions $Px_{\min, \max}(0, x_0) = 0$ and boundary conditions $Px_{\min, \max}(t, x_{\min}) = Px_{\min, \max}(t, x_{\max}) = 1$.

$$\lim_{t \rightarrow \infty} Px_{\min, \max}(t, x) = 1. \quad (34)$$

Coefficients $K_1(x_0)$, $K_2(x_0)$ in equation (33) as determined in accordance with expectation rate depreciation in the initial time and a spectral density of the process $N(t)$ by the formula: $K_1(x_0) = C + \lambda \Delta_0$; $K_2(x_0) = \frac{1}{2} \sigma_N^2$.

Marked the one-dimensional moments in time limits to achieve a

$$T_n = T_n(x_{\min}, x_0, x_{\max}) = \int_0^{\infty} t^n \frac{\partial Px_{\min, \max}}{\partial t} dt,$$

Equation (33) differentiating both parts by t , multiplying result by $\exp(jvt)$ and then integrating in t from 0 to ∞ , returned the following equation for the characteristic function:

$$-jv \Theta_{x_{\min}, x_{\max}} = K_1(x_0) \frac{\partial \Theta_{x_{\min}, x_{\max}}}{\partial x_0} + \frac{1}{2} K_2(x_0) \frac{d^2 \Theta_{x_{\min}, x_{\max}}}{dx_0^2}$$

$$\Theta_{x_{\min}, x_{\max}}(jv, x_0) = - \int_0^{\infty} \frac{\partial}{\partial t} Px_{\min, \max}(t, x) e^{jvt} dt. \quad (35)$$

Equation (35) to find the first moments of time reaching the limits of tolerance parts and used to determine the dimensional stability of the instrument (Fig. 1).

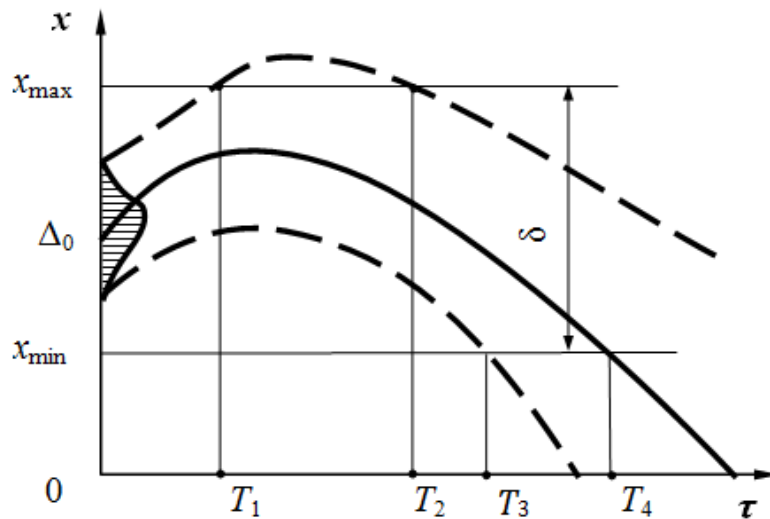


Fig. 1. Moments of time reaching the limits of tolerance parts

To check the adequacy of the models developed experimental unit for measuring tool wear. Based on performance testing tools in industrial conditions obtain wear curves cutting plates, their example shown in Fig. 2. The probability of adequacy of mathematical models is 0,71.

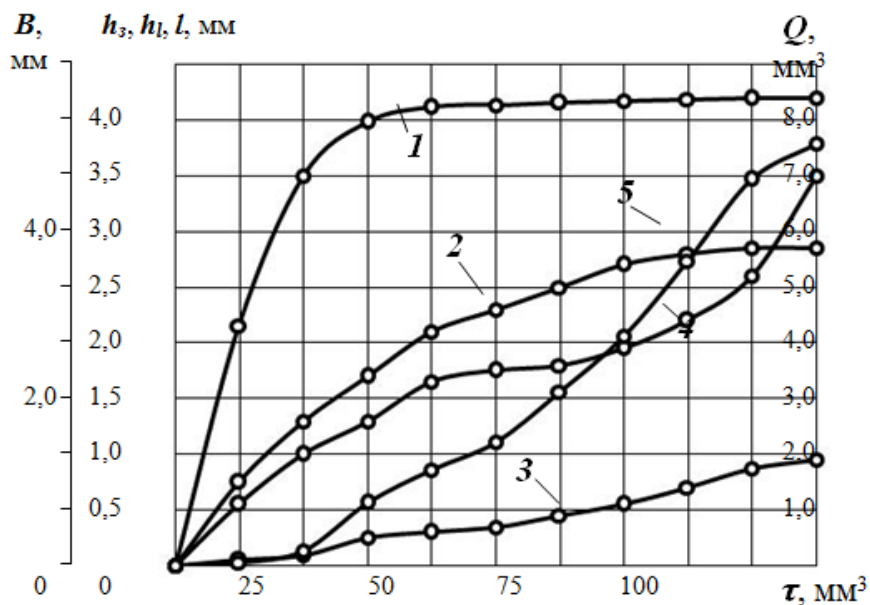


Fig. 2. Crooked wear plate cutting SNMG 380932
(1 – width, 2 – length 3 – deep hole, 4 – width chamfer wear on the rear surface, 5 – the amount of material the tool is withdrawn from the front surface)

On the basis of studies have developed analytical calculation based cutting tool wear on the front and back surfaces of the parameters of the operation, which averages to estimate the period of stability instrument, proposed method of determining the dimensional stability of the instrument with a given probability (for finding the size of workpieces in a given field admission), which depends on tool wear during the finishing details.