

$$\begin{aligned} & \left(\frac{dQ(t)}{dt} + \frac{Q(t)}{F} \right) = H(t) - Q_H(t) \\ & \left(\frac{dQ(t)}{dt} + \frac{Q(t)}{F} \right) = H(t) - Q_H(t) \end{aligned} \quad (1)$$

$H(t)$,

$$1 \quad (1)$$

(t)

$$(1)$$

$$(1)$$

$$\begin{aligned} & Q(t) \\ & Q_H(t) \end{aligned}$$

[1]:

$$\frac{dQ(t)}{dt} = k(Q(t) - Q_H(t)),$$

$$\begin{aligned} & \frac{dQ(t)}{dt} - k(Q(t) - Q_H(t)) = 0 \\ & \frac{dQ(t)}{dt} - kQ(t) + kQ_H(t) = 0 \end{aligned}$$

$$k = \frac{1}{F}$$

$$F = \frac{1}{k}$$

$$[2,3]: \quad Q_H(t) - H(t) = 0$$

$$\begin{aligned} & \frac{dQ(t)}{dt} + \frac{Q(t)}{F} = H(t) - Q_H(t) \\ & \frac{dQ(t)}{dt} + \frac{Q(t)}{F} = H(t) - Q_H(t) \end{aligned}$$

Q_H ,

$$[3,4].$$

[3,4]:

$$= \dots + \dots - \dots^2, \quad (1)$$

$Q -$
, , -
)

() ;

(

[3,4]:

$$= +\Delta = +\alpha Q^2, \quad (2)$$

-

(

-

);

$\Delta -$

;

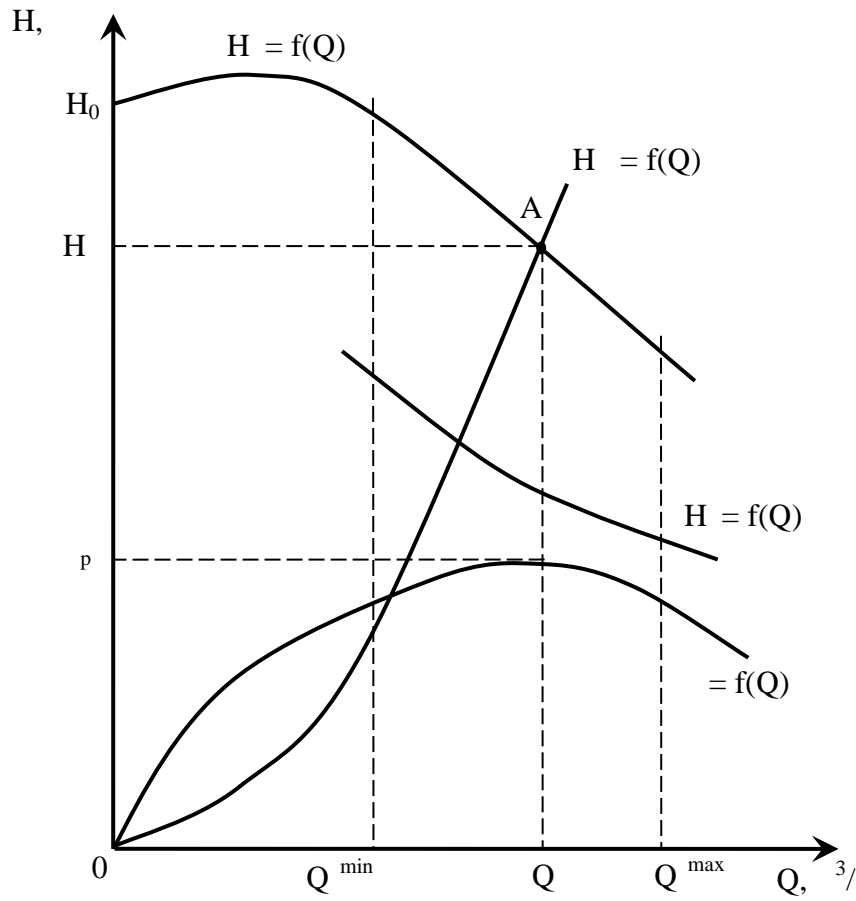
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(1)

(2).

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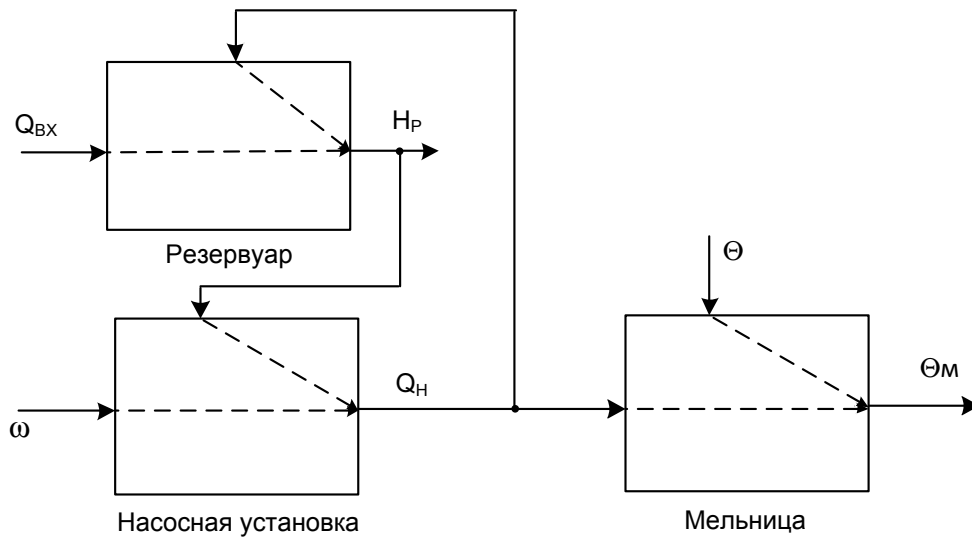
2 -

$$H \leq H .$$

$H .$

$$- Q_P^{\min} < Q_P < Q_P^{\max} .$$

(3)



3 -

(.3):

- ; Q_H ; θ .

(.3):

- Q ;
- ;
- ω ;
- Q_H .

(.3):

- Q_H () ;
- ;
-) ;
- θ (

(.4)

- P ;
- Q_H ;
- θ .

(.4)

P

Q ,

Q_H .

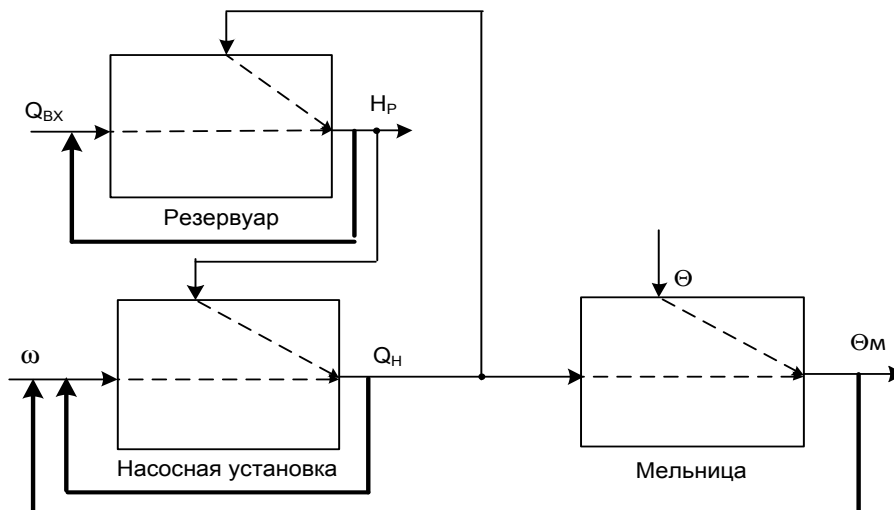
(.4).

Q_H

(
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Q_H)

θ (.4).



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